

ASM Robots & Automation Engineering

Via Crispi,20 - 36075 Montecchio Maggiore (Vi) Tel. +39 0444 696493 - Fax. +39 0444 498847 info@asmrobotics.com - www.asmrobotics.com

Quotation

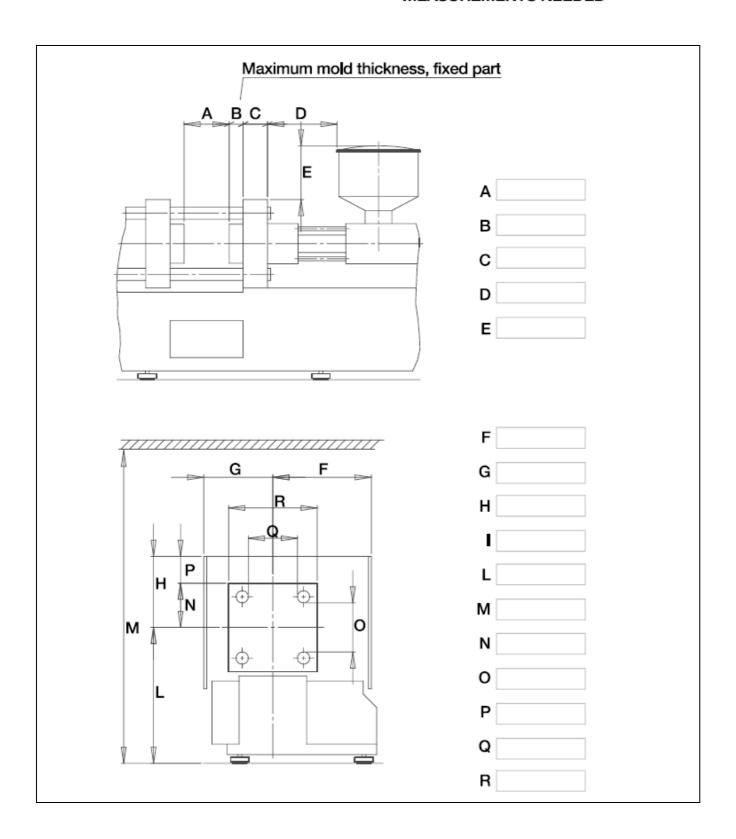
COMPANY NAME*:			
COMMERCIAL PERSO	N'S		
Name and surname*:			
Position:			
TECHNICAL PERSON CONTACT DETAILS	s		
Name and surname*:			
Position:			
INVOICE ADDRESS			
City*:			
Street name and number*:			
Postal code*.		Province*:	State*:
DELIVERY ADDRESS			
City*:			
Street name and number*:			
Postal code*.		Province*:	State*:
Requeoted delivery date:			



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MEASUREMENTS NEEDED





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Piece extraction:	Fixed plate	○ Loose Plate
Side the piece will be unloaded from:	Operator	Opposite the operator
To load the mould:	Operator Transpallet	Opposite the operator Fork lift
Holes for fixage:	○ Yes	○ No
Type of press:		
Mould Cycle Sec.:		
Type of robot:		
Sprue length, Piece height (drawing):		
L		
Mould Descrip	tion:	
Sa	mple O Drawin	90
	Dimension:	
	Weight (Kg)	
	Total cycle time (s)	
	Open press time (s)	



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Taken from:	Fixed line	○ Cell
Press / Robot interface:	O Euromap 12	C Euromap 67
Electrical power supply:	tension V:	
	frequency Hz:	
Main rotation		
Gripping apparatus:	Standard with suction cups	Other
Conveyor Belt	nodel (see internet site):	
	length (mm):	
	used length (mm):	
	width (mm):	
	height (mm):	
	○ with edges ○ 3 (m/min) ○ 6 (m/n	○ without edges